Magnetic – inductive flowmeter

MIA-C, MIA-S



User guide



Rev. 1.1, © ELA, spol. s r.o.

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1. Introduction

MIA magnetic-inductive flowmeters (compact version: MIA-C, separated version: MIA-S) are precise measuring devices intended for the measurement of liquid flow of electrically conductive media. The meters may be used for measurements, registration, dosing, mixing, etc.

MIA application

- Water management, drinking and waste water measurement
- Chemical, textile, paper, mining industry
- Food industry
- Power engineering and heating plants
- Agriculture

MIA advantages

- Independent of power supply fluctuation and line voltage interference
- Independent of pressure, temperature and density, etc of the media
- No pressure losses
- No disturbances of measured liquid consistency



Do not install where

- Liquid conductivity is below 5 μS/cm (20 μS/cm for demineralized water)
- Partly filled pipe is possible
- Non lamina flow occurs

Caution: For flow velocity below 0.3 m/sec worsening of accuracy must be considered.

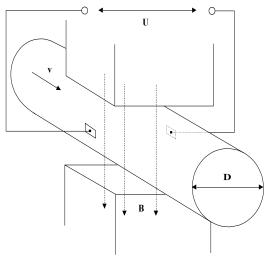
The principle of inductive sensor operation

The measurement is based on the principle of Faraday's law of electromagnetic induction. In compliance with this law, electric voltage is induced in an electrically conductive body, which moves across a magnetic field. The following equation is applied for voltage to be induced (generally):

 $U = B \times D \times v$ where:

U is inductive voltage D is piping diameter B is magnetic induction v mean flow speed vector

If magnetic induction B and piping diameter D are constant, then induction voltage is proportional to the mean flow speed. Liquid is flowing via a flowmeter perpendicularly to the direction of the magnetic field. Electric voltage which is monitored by two electrodes placed perpendicularly to both magnetic field and flow is induced by a stream of liquid with minimum electrical conductivity. Excitation current with a rectangular waveform is generated in a converter and fed to sensor coil windings generating the flowmeter magnetic field. The forced-current system provides constant excitation under all conditions that can occur during the operation.



2. Specifications

2.1. Measurement conditions

Measurement is independent up on:

- Liquid temperature and pressure
- Liquid density and viscosity
- Solids contents
- Usual level of magnetic field interference

For maintaining the MQI accuracy and reliability, it is necessary to meet the following conditions:

- Electrical conductivity of medium $\geq 5 \mu$ S/cm, for demineralized water $\geq 20 \mu$ S/cm
- Liquid velocity min. 0.3 m / sec, max. 12 m / sec.
- Steady flow section performance no DN change bevel pipe part(s) of maximum 8°.
- Steady flow section length 5 DN upstream / 3 DN downstream (from sensor)
- Fully filled sensor profile with liquid measured.
- High quality operational contact between the sensor and liquid measured.

Measurement accuracy is interfered by:

- Gassing of measured liquid and air bubbles
- Strong stray earth currents
- Liquid turbulence in the sensor
- Solids of magnetic metals in the medium measured

Sensor option:

- A measuring pipe is made of non-magnetic material with welded flanges and assembly clamps. An insulating liner with required properties is installed inside the pipe (according to the medium used). A system of driving coils generating the required magnetic field is directly fixed on the measuring pipe body.
- A pair of electrodes located opposite and passing through the measuring pipe with liner is made of high-grade steel and/or other material (according to the required chemical resistance against the medium being measured).
- The complete electrical section is assembled in steel housing (welded) with a neck for internal cabling.
- Remote version: A signal cable with the standard length of 8 m/ Cu type 2 × 2 × 0.25 mm² is attached to the neck and the cable passes through a cable seal (also other lengths are available).
- Compact version: The instrument box body is attached to the neck.
- The housing welding makes it possible to achieve a high-grade protection and surface finish provides a steady climate resistance.

Converter option:

 Control and evaluation electronics is assembled into robust aluminium housing with IP67 protection, or in case of remote version, protection of sensor is IP68.

Additional options:

• Multi-point calibration of the measuring range. The flowmeters are usually calibrated in 3 points. On the customer's request, the number of calibration points can be increased.

- Higher sensor protection IP 68: the requirement must be precisely defined (i.e. immersion depth and time, and/or explosive zones).
- Higher PN, and/or different sensor built-in lengths, different flange options (DIN, ANSI, etc.), after consultation of your supply.

3. Connection and assembly

Converter connection to power supply must be performed in compliance with the standards and rules:

- Connection of electrical instruments and appliances.
- Protection against electric shock.
- Heavy current distribution network in industrial plants.
- Safety operational rules for electrical installations operated by low-level experienced personnel.

If requested our Service Division will carry out commissioning. If work is done by any different organisation, the warranty can be cancelled in the case of such unauthorised work.

Electrical protection allows the use of the instrument in all kinds of active, passive and complex environments, and after an agreement with us, it is possible to carry out some additional modifications even for severe climaticconditions.

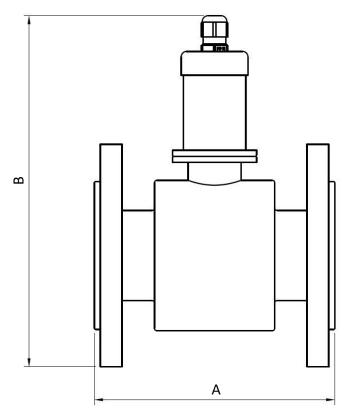
Signal and output cable routing should not be located near power output distribution network or in common ducts.

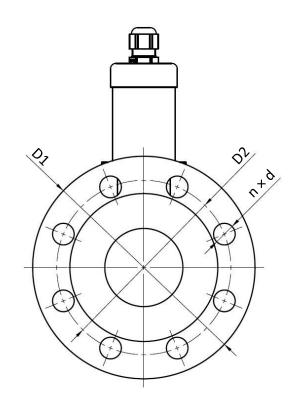
| Table for 1 m / s flowrates | | | | |
|-----------------------------|--------|--------|--------|--|
| DN | m³/h | l/min. | l/s | |
| 10 | 0,283 | 4,712 | 0,079 | |
| 15 | 0,637 | 10,62 | 0,177 | |
| 20 | 1,131 | 18,85 | 0,314 | |
| 25 | 1,767 | 29,452 | 0,491 | |
| 32 | 2,895 | 48,255 | 0,804 | |
| 40 | 4,524 | 75,398 | 1,257 | |
| 50 | 7,069 | 117,81 | 1,964 | |
| 65 | 11,946 | 199,1 | 3,318 | |
| 80 | 18,096 | 301,59 | 5,027 | |
| 100 | 28,274 | 471,23 | 7,854 | |
| 125 | 44,179 | 736,31 | 12,272 | |
| 150 | 63,617 | 1060,3 | 17,671 | |
| 200 | 113,1 | 1885 | 31,42 | |
| 250 | 176,71 | 2945,2 | 49,087 | |
| 300 | 254,47 | 4241,2 | 70,686 | |
| 350 | 346,36 | 5772,7 | 96,211 | |
| 400 | 452,39 | 7539,8 | 125,66 | |
| 450 | 572,26 | 9537,5 | 158,96 | |
| 500 | 706,86 | 11781 | 196,35 | |
| 600 | 1017,9 | 16965 | 282,74 | |
| 700 | 1384,7 | 23079 | 384,65 | |
| 800 | 1809,6 | 30159 | 502,65 | |
| 900 | 2289,1 | 38151 | 635,85 | |
| 1000 | 2827,4 | 47124 | 785,4 | |

Constructional dimensions and weights of inductive sensors

| Constructional dimensions and weights of inductive sensors | | | | | | | | |
|--|----|-----------------|------|------|------|----|----|--------|
| DN | PN | Dimensions [mm] | | | | | | weight |
| DN | | Α | В | D1 | D2 | d | n | [kg] |
| 10 | | | 266 | 90 | 60 | 14 | 4 | 2,5 |
| 15 | | | 268 | 95 | 65 | 14 | 4 | 2,5 |
| 20 | | 150 or | 273 | 105 | 75 | 14 | 4 | 3 |
| 25 | | or 200 | 280 | 115 | 85 | 14 | 4 | 3,5 |
| 32 | | | 293 | 140 | 100 | 18 | 4 | 5 |
| 40 | | | 298 | 150 | 110 | 18 | 4 | 6 |
| 50 | | | 304 | 165 | 125 | 18 | 4 | 7 |
| 65 | | 200 | 322 | 185 | 145 | 18 | 4 | 8 |
| 80 | | | 337 | 200 | 160 | 18 | 8 | 9,5 |
| 100 | | 250 | 358 | 220 | 180 | 18 | 8 | 12 |
| 125 | | 230 | 389 | 250 | 210 | 18 | 8 | 15 |
| 150 | 16 | 300 | 418 | 285 | 240 | 22 | 8 | 20 |
| 200 | 10 | 350 | 488 | 340 | 295 | 22 | 12 | 36 |
| 250 | | 400 | 543 | 405 | 355 | 26 | 12 | 58 |
| 300 | | 500 | 600 | 460 | 410 | 26 | 12 | 70 |
| 350 | | 500 | 655 | 520 | 470 | 26 | 16 | 85 |
| 400 | | | 728 | 580 | 525 | 30 | 16 | 100 |
| 450 | | 600 | 770 | 640 | 585 | 30 | 20 | 120 |
| 500 | | 000 | 863 | 715 | 650 | 33 | 20 | 160 |
| 600 | | | 983 | 840 | 770 | 36 | 20 | 190 |
| 700 | | 700 | 1040 | 910 | 840 | 36 | 24 | 260 |
| 800 | | 800 | 1163 | 1025 | 950 | 39 | 24 | 350 |
| 900 | | 900 | 1258 | 1125 | 1050 | 39 | 28 | 450 |
| 1000 | | 1000 | 1398 | 1255 | 1170 | 42 | 28 | 550 |

DN 10 – DN 150 \rightarrow A ± 5 mm, DN 200 – DN 1000 \rightarrow A ± 10 mm





Signal cable (connection between sensor and converter of the MIA-S):

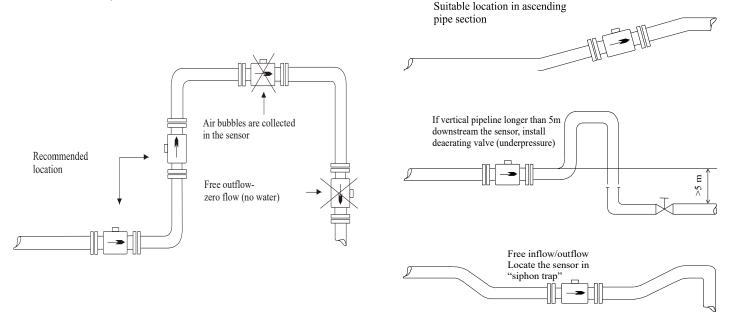
- Signals which are transmitted from a sensor electrode circuit to the converter will be in a range of millivolts. They will be very sensitive to magnetic and electrostatic interference from neighboring high-voltage cables, power supply cables and high power output motors, etc. The interference is mainly compensated for by the converter connection, nevertheless if possible, it is necessary to prevent all spurious signals.
- The signal cable is of a special construction and length and is a part of the shipment, its length should not be changed (for certificated meter must not be changed). The proper cable connection to the converter is important; doing so may cause measurement failures. Special requirements are laid on shielding, and the measurement precision depends on its quality.
- The cable must not be extended.
- The shielding must be well insulated on the whole route from ground and the other metal subjects. It is recommended that the cable is located in a separate conduit or trays.

Sensor location and its position in piping:

- The inductive flowmeter sensor can be installed in any position according to requirements, however for horizontal assembly, the electrode axis must always be horizontal.
- Sensor must remain full of liquid.
- It is recommended that the flow direction should follow the arrow on the sensor cover; the converter is also
 preset for this direction. On the operating meter, it is possible to adjust the reverse flow direction by changing
 the MIA converter parameter.
- Bolts and nuts verify if there is a sufficient space for their installation near flanges.
- Vibration and deflection of piping fix the piping on both sides from the flowmeter to avoid any deflection and vibrations.
- If you install any pipes with higher internal diameters, install a reducer; this will provide an axial shift without increased mechanical stress of piping and sensor flanges.

- To improve flow, use only the recommended straight lengths upstream (5DN) and downstream of the sensor (3DN). Any change of a diameter with an angle up to 8° is excluded from the above-mentioned straight lengths. Suitably assembled flow deflectors and a combination of diffusers are used in more sophisticated installations.
- When you install the sensor in insulated piping (e.g. glass, artificial mass, etc.), use proper sealing ground rings.
 A conductive connection between a sensor ground point and the liquid to be measured is needed for a proper measurement.

Recommended positions for sensor installation:



To avoid any measurement errors which are caused by air bubbles or failures on the lining, pay attention to the following recommendations:

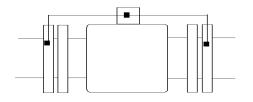
- During assembling correctly seat the sensor, tighten screws uniformly and move on a diagonal one after another.
- It should be noted that the parallelism of flanges has a greater effect on packing than excessive tightening forces on curved and seated flanges.
- The sensor must be installed inside piping so that the axis of sensor electrode is always horizontal.
- A PTFE (teflon) lining calls for extra care during handling and assembly. During installation/operation avoid excessive under pressure in pipes. Please do not change and damage the outlet extension on both ends of the sensor. The sensors are shipped from the factory with special covers to avoid any shape deformations. (PTFE elastic memory should cause a partial compensation in future). Please remove the covers just before installation, and when you insert it between counter flanges, replace by a number of smooth metal sheet pieces which are removed just before tightening the bolts.
- Packing The extended part of lining does not operate properly as a seal, hence appropriate packing must be
 inserted between sensor and pipeline. If the packing protrudes into a flow profile at any point, this will cause
 turbulence and reduce the measurement quality.
- During installation, make sure the sensor slides into piping if the pipeline is not flexible enough. It is
 recommended that installation inserts (especially for greater internal diameters) should be used. During
 installation of the sensor, counter flanges must not be welded (danger of the sensor lining failure).

MIA grounding:

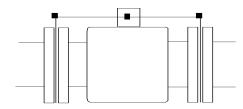
 For reliable and proper operation of the inductive meter, it is necessary to use high-quality protective grounding. Internal flowmeter cables and power supply PE (PEN) conductors provide protective grounding. Working grounding is also provided via internal cables and a high-quality connection of the sensor body with two metal pipe counter flanges. It is recommended that a connection made with M6 welded screws or bored threaded holes is used. The connection under flange fixing screws is not recommended because of possible corrosion resulting in measurement failures.

- When assembled into piping made from non-conductive material (or with non-conductive lining), it is necessary to provide working grounding with liquid by a different method, e.g. by grounding rings valid for DN 10 ÷ DN 40. The rings can be ordered from factory, their material and chemical resistance must comply with the liquid to be measured usually produced from the same material as sensor electrodes. The flowmeters from DN 50 ÷ DN 1000 are equipped of grounding electrode. Function of grounding electrode is same as grounding ring.
- When assembled, it is necessary to insert the packing on both sides of the grounding ring. Make sure that no
 parts will protrude into an internal sensor profile (turbulence).

Drawing of sensor working grounding inside pipeline



Use of grounding rings –valid for DN 10 ÷ DN 40



Electrodes:

- The electrode material must be selected according to its chemical resistance of the liquid to be measured.
- The electrode purity can affect the measurement precision, and high impurity concentration can affect the measurement process (liquid insulation).
- Immediately after shipping, it is not necessary to clean the electrodes before installing the sensor inside piping. Clean with a fine cloth, or use a chemical detergent. Avoid any damage of the lining! If the electrodes must be cleaned during operation, either mechanical or electrolytic methods may be used. Mechanical cleaning can only be used for a suitable sensor assembly, otherwise dismantle the sensor from the pipeline. After cleaning reinstall the sensor.
- Any electrolytic method is advantageous for its simplicity, however it can only be applied for the contamination that can be removed by electrolysis (low contamination and deposit).
- All detailed instructions are available from the flowmeter manufacturer on request.
- If a flowmeter operates under normal conditions, for most liquids it is not necessary to clean flowmeters during their life, only self-cleaning by flowing liquid is satisfactory (a recommended velocity is over 3 m/s).

4. MIA commissioning

Checking installation and connections:

- Proper sensor and grounding.
- Tightening all cable connection clamps and plug in all connectors.
- For MIA-S verify the completeness of the shipped set according to the serial numbers of sensor and converter.
- Verify proper supply voltage; see the label on the converter.
- Verify proper electrical protection.
- If the installation is fault-free, fill the pipeline with liquid and verify the sensor tightness inside the pipeline.
 After short washout, switch the system on-off-on.

Service:

- The commercial, service and technical assistance for MIA is provided by Ela Brno, Ltd in cooperation with Michal Nos, tel.: +420 602 550 723, email: <u>ahmnos@email.cz</u>.
- The Service Division secures all activities that are related to the commissioning and all parameter changes at site (with the exception of certificated meters).

 Ela Brno, Ltd can authorise another organisation to provide service. The organisation must be able to submit the appropriate approval/certificate on request. The producer carries out recalibration of all meters and their repairs.

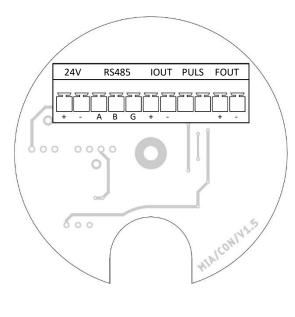
The additional devices are intended for remote control of the converter output signals (displaying and processing). The additional devices are not usually included in MIA shipment, but their type should be approved by the manufacturer. In such a case, the manufacturer is only responsible for the suitability of input parameters, and all other parameters are set according to the manufacturer's specifications of the additional devices.

If a set is ordered without installation, the sensor is packed in corrugated paper and the converter is enclosed in a cardboard box or wooden palette.

5. Technical data

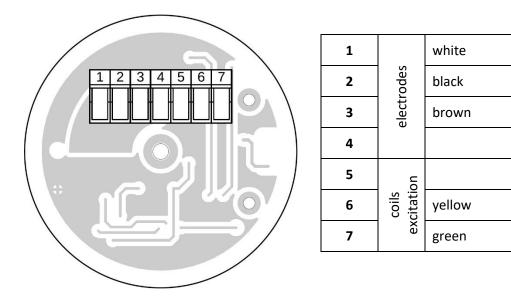
| Option | MIA-C: compact version |
|--------------------------------------|---|
| | MIA-S: separated version (sensor installed under ground or under liquid |
| | level), fixed cable, cable length according to the order (max. 50 m) |
| Nominal sizes | flange DN 10 ÷ 1000 mm, without flanges DN 10 ÷ 100 mm |
| Insulation class of excitation coils | class E |
| Connection | flanged DIN (ANSI, BS, JIS) / hygienic - food DIN 11 851 |
| Maximum pressure | standard 1,6 MPa (0,6 / 1,0 / 2,5 / 4,0 MPa) |
| Liner material | hard + soft rubber DN 10 ÷ DN 1000 / teflon PTFE DN 10 ÷ DN 500 |
| Electrodes | stainless steel 316Ti (Hastelloy / Tantal / Titan / Platinum) |
| Outer casing and flanges | carbon steel standard (stainless steel 304, 321) |
| Flow tube | stainless steel 321 |
| External coating | acrymetal multi component lacquer / polished stainless steel |
| Protection | IP67-NEMA5 (compact version) / IP68-NEMA6 (separated version) |
| Media temperature | compact version: 0 ÷ 90 °C |
| | separated version: hard rubber (0 ÷ 90 °C), PTFE (-20 ÷ 130 °C) |
| Accessories options | sensor grounding ring for plastic pipe for DN 10 ÷ DN 40 |
| | sensor grounding electrode for DN 50 ÷ DN 1000 |
| Special option | food industry stainless steel version – teflon lining, fitting DIN 11 851 |
| | flange version with stainless steel cover – teflon / rubber lining |
| | flange all-stainless steel version – teflon / rubber lining |
| | without flange version – teflon / rubber lining |
| Flow direction | both direction |
| Suppression of small flows | yes |
| Empty pipe detection | yes |
| Electrical conductivity of medium | ≥5 μS/cm, for demineralized water ≥20 μS/cm |
| Accuracy of measurement | 0,5 % of measured value + 2 mm/s (reference conditions) |
| Communication port | RS 485, MODBUS RTU (instantaneous reading, parameters setting and |
| | calibration) |
| Distance from master | to 1000 m |
| Main unit protection | IP67 - NEMA5 |
| Ambient temperature | -20 ÷ 60 °C |
| Power supply | 9 ÷ 36 V DC / 10 W |
| Analog output | passive, 4-20 mA, max. 500 Ω |
| Pulse output | passive, optical relay, max. 30 V / 60 mA |
| Frequency output | passive, opt coupler, max. 26.4 V DC / 2 mA - setting up to 2 kHz |
| | (for calibration, dosing applications, etc.) |

Control unit terminal board, input / output connection and basic functions:



| 24V | power ing | + 9÷36V/10W - |
|-------|---------------------|---|
| RS485 | RS485 | A B G (SHIELD) |
| ΙΟυΤ | current loop | + 4 ÷ 20mA - |
| PULS | pulse output | optical relay, max. 30 V, 60 mA |
| FOUT | frequency output | + optocoupler, max. 26 V DC, 2 mA, up to 2 kHz |

Sensor terminal board:



We recommend connecting the wires, screwing on the covers, and then tightening the bushing. It prevents unwanted twisting of wires.

DECLARATION OF CONFORM C

Product: MQI 99 - C/S - SMART, MQU 99 - C/S - SMART, MHU 99 - C/S - SMART, MI, MIA, MIE, ESONIC, PU, CU

Producer: ELA, spol. s r.o.

Headquarter: Mikulovská 1, 628 00 BRNO, Czech Republic, ID: 46969063, VAT: CZ46969063 Office, Workshop: Sokolova 32, 619 00 Brno, Czech Republic

Product description and designation: flow and level measuring instruments

This Declaration of Conformity is issued under the sole responsibility of the manufacturer.

The above product is in compliance with the following laws:

• Act No. 90/2016 Coll., On technical requirements for products

• Council Directive 2014/35 / EU (Government Regulation No. 118/2016 Coll. On conformity assessment of electrical equipment intended for use within certain voltage limits during their delivery to the market)

• Council Directive 2014/30 / EU (Government Regulation No. 117/2016 Coll., On Conformity Assessment of Products in terms of Electromagnetic Compatibility when Delivering to the Market

The following technical standards and specifications were used in the assessment:

- ČSN EN 61010-1 ed. 2
- ČSN EN 61326-1 ed. 2
- ČSN EN 61000-4-2 ed. 2
- ČSN EN 61000-4-3 ed. 3
- ČSN EN 61000-4-4 ed. 3
- ČSN EN 61000-4-5 ed. 3
- ČSN EN 61000-4-6 ed. 4
- ČSN EN 61000-4-8 ed. 2
- ČSN EN 61000-4-11 ed. 2

The device may only be installed, commissioned and repaired by a person instructed and authorized in accordance with applicable regulations.

Issued in : Brno

Date of issue: 14.6.2019

| Ing. Milan Vlček Director of Company | ELA, spôl. s r.o. ③ provozovna: Kšírova 186, 619 00 Brno tel/fax: 5-4321 4755 úř. sídlo: Mikulovská I, 628 00 Brno 1ČO: 46969063 DIČ: 289-46969063 |
|---|---|
| Signature : | Vear , |



CERTIFIKÁT

Certifikační orgán systémů managementu č. 3053 TÜV SÜD Czech s.r.o.

potvrzuje, že společnost



ELA, spol. s r.o. Mikulovská 1 CZ – 628 00 Brno IČ: 46969063

zavedla a používá systém managementu kvality v oboru

návrh, výroba, montáž a servis elektronických měřicích přístrojů

Na základě vykonaného auditu, zpráva č. 12.156.642

bylo prokázáno splnění požadavků normy

ČSN EN ISO 9001:2016

Tento certifikát je platný od **04.06.2019** do **02.06.2022** Registrační číslo certifikátu **12.156.272**

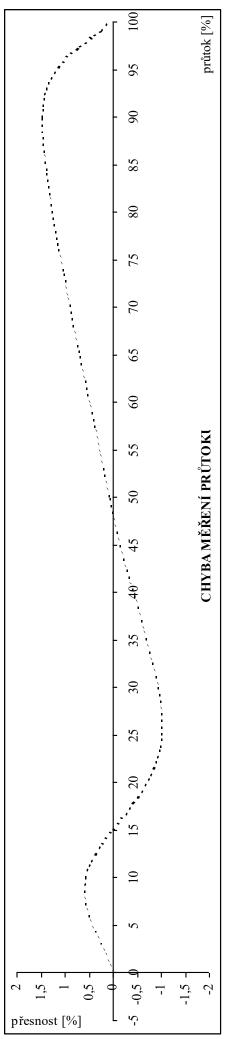




Praha, 04.06.2019

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6. Adjustment protocol

Customer: Measuring site: Serial number: Measurement range: ČMI certificated meter Test room: Sensor DN: mm Sensor PN: MPa Sensor electrodes: stainless steel Sensor lining: rubber Sensor max. temp.: °C Sensor cable length: 10 m Sensor elect. protection: IP Sensor measured medium: water Sensor exciting current: mA

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Converter type:

Outputs:Converterforced current:Converterrelay 1:Converterrelay 2:Converterrelay 3:Converterrelay 4:Converterdata line:

Calibrated by: Date: Constant: Note:

7. Warranty

Instrument:

Serial number:

Dispatch date from storehouse:

Commissioning:

Date:

Company:

The manufacturer warrants that the instrument corresponds to Technical Specifications, and to be free from defect in workmanship and material and complete. During installation and commissioning, all hints that are presented in Technical Specifications and related norms and safe work rules must be met. The supplier is fully responsible for completeness and proper product operation. The customer during the acceptance of product must check the completeness.

The manufacturer does not warrant – before the warranty period will elapse – for damages caused by improper or unqualified operation or using the flowmeter under such conditions that do not correspond to those given in Technical Specifications. The manufacturer reserves to perform all warranty and after-warranty repairs. For warranty repairs, please submit your warranty sheet.

If the conditions presented in both Technical Specifications and Warranty are met, the warranty period is twelve months from the date of commissioning by the manufacturer or another authorised company, however at most 18 months from the date of shipment to the site.

Flowmeter repair:

Date:

Company:

Flow repair:

Date:

Company:

8. MODBUS

MODBUS protocol implementation conforms MODBUS Application Protocol Specification, version 1.1, modbus.org 12/06/02.

Device comes with default settings that are:

- slave address set to 1,
- baud rate 9600 Bps,
- 8 data bits, even parity, one stop bit.

Each MIA register takes two MODBUS registers, i.e. each MIA register is 32 bits long. These 32 bits are interpreted as an integer with or without a sign or as a floating point number with single precision. Double precision floating point numbers are stored in eight bytes, so they are transmitted in four MODBUS registers.

The MODBUS register with lower address is transferred first.

Device implements MODBUS functions 0x03 and 0x10.

Coding of Integers:

MODBUS register with higher address MODBUS register with lower address 31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0 sign for signed integer Coding of floating point numbers: Floating point numbers compatible with Single type defined by IEEE 754. MODBUS register with higher address MODBUS register with lower address 31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0 significant field exponent sign Floating point numbers compatible with Double type defined by IEEE 754. MODBUS register with MODBUS register with the highest address of four the lowest address of four 52 51 -----0 63 62 ----significant field exponent sign

MODBUS registers:

All registers are read only. For security reasons writing to registers is a bit more complex than reading, so the manufacturer provides configuration software which is free to charge.

| Add | ress | Tupo | Namo | Unit | Description | | |
|-------------|------|--------------|------------------------|----------------|--|--|--|
| [dec] [hex] | | Туре | Name | Unit | Description | | |
| 100 | 0064 | unsigned int | Slave address | | Slave device address in range from <u>1</u> to 247. | | |
| 102 | 0066 | unsigned int | Baud rate | Bps | Transmission rate, one value from 1200, 2400, 4800, <u>9600</u> , 14400, 19200, 28800, 38400, 57600. | | |
| 104 | 0068 | unsigned int | Parity | | Transmission parity check, one value from $0 = no$ parity, <u>1 = even</u> , 2 = odd, 3 = no parity, two stop bits. | | |
| 106 | 006A | unsigned int | Pause | μs | Additional time in microseconds to extend silent interval between server request and slave response. | | |
| 108 | 006C | unsigned int | Response time limit | μs | If slave device is not able to prepare response until this time expires, response isn't be send. | | |
| 110 | 006E | unsigned int | Secondary flow unit | | Unit of register $1024_{(10)}$. Can be one from: $0 = I/s$, $1 = m^3/h$, $2 = m^3/s$, $3 = I/min$, $4 = UKgaI/s$, $5 = USgaI/s$. | | |
| 1000 | 03E8 | float | Q | l/s | Current flow, in litres per second. | | |
| 1002 | 03EA | unsigned int | Main status | | Bit 15:Parameter memory reading error. Neither measurement nor service function can be started.Bits <7, 0>:State of device: 0x00 idle time, 0x80 measurement is in progress, 0x80 to 0xFF service function is in progress. | | |
| 1004 | 03EC | unsigned int | Alarms | | Bit 31: excitation circuit failure, Bit 29: unfilled pipe error. | | |
| 1008 | 03F0 | float | СМ | | Main calibration constant (significant field) | | |
| 1010 | 03F2 | signed int | CE | | Main calibration constant (exponent) | | |
| 1020 | 03FC | float | Velocity | m/s | Flow velocity in meters per second. | | |
| 1022 | 03FE | signed int | Temperature | °C | Converter temperature. | | |
| 1024 | 0400 | float | Q in secondary unit | | Current flow in unit by register 110. | | |
| 2000 | 07D0 | double | S+ | m ³ | Forward volume counter. | | |
| 2004 | 07D4 | double | S- | m ³ | Backward volume counter. | | |
| 4002 | 0FA2 | unsigned int | Back | | Flow direction reversal. QM is measured flow obtained by reading a register 1000 (or 1024) and Q is a real flow. If Back = 0 than Q = Q_m otherwise Q = $-Q_m$. | | |
| 4004 | 0FA4 | float | Cutoff low | % | Lower and upper limits for small flow | | |
| 4006 | 0FA6 | float | Cutoff high | % | suppression (hysteresis algorithm), in percentage of calibration range (register 8100 ₍₁₀₎ . Usual values are 0.4 and 0.6%. | | |
| 8002 | 1F42 | float | DN | mm | Nominal sensor size. | | |
| 8100 | 1FA4 | float | Calibrated range | l/s | | | |
| 9002 | 232A | unsigned int | Device type | | Device type, 2000 = MIA flowmeter | | |
| 9004 | 232C | unsigned int | Firmware version | | for example 0x01090C00 = 1.9.12.0 | | |
| 9006 | 232E | unsigned int | Serial number | | | | |